Dual Display PID Temperature Controllers



TCN Series

PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- Dual digital display (PV/SV)
- 100ms high-speed sampling rate and $\pm 0.5\%$ display accuracy
- Switch between relay output and SSR drive output
- SSR drive output (SSRP function) control options: ON/OFF control, cycle control, phase control
- Compact design with large display panels for easier reading
- Connector plug types offer easier wiring and maintenance (TCN4S-□-P)

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ▲ symbol indicates caution due to special circumstances in which hazards may occur.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
 Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use or store the unit in the place where flammable/explosive/ corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

- 03. Install on a device panel to use.
 - Failure to follow this instruction may result in fire or electric shock.
- 04. Do not connect, repair, or inspect the unit while connected to a power source.
 - Failure to follow this instruction may result in fire or electric shock.
- 05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

 ${\bf 06.\ Do\ not\ disassemble\ or\ modify\ the\ unit.}$

Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact failure.

- 02. Use the unit within the rated specifications.
 - Failure to follow this instruction may result in fire or product damage
- **03.** Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock.
- Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
- For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates $\,$ strong magnetic force or high frequency noise.

 Install a power switch or circuit breaker in the easily accessible place for supplying or
- disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- 24 VAC~, 24-48 VDC= power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments. Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website

T C N 0 2 - 3 2 5 - 3	
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Digit

4: 4 digit

Size

S: DIN W 48 \times H 48 mm M: DIN W 72 \times H 72 mm

H: DIN W $48 \times H$ 96 mm

L: DIN W 96 \times H 96 mm

3 Option in/output

Power supply

2: 24 VAC 50/60 Hz, 24-48 VDC 4: 100-240 VAC 50/60 Hz

6 Control output

R: Relay + SSR drive

2: Alarm 1/2

Wiring type

No mark: Bolt

P: Connector plug connection

Product Components

· Product (+ bracket)

· Instruction manual

Sold Separately

• Terminal protection cover: RSA / RMA / RHA / RLA-COVER

Specifications

Series		TCN4□-22R-□	TCN4□-24R-□				
		24 VAC~ 50/60 Hz					
Powers	upply	24 - 48 VDC== 100 - 240 VAC~ 50/60 Hz					
Permissible voltage range		90 to 110 % of rated voltage					
Power co	onsumption	AC: ≤ 5 VA, DC: ≤ 3 W	≤5 VA				
Samplin	g period	100 ms					
Input sp	ecification	Refer to 'Input Type and Using Ran	ge.				
Control	Relay	250 VAC∼ 3 A, 30 VDC== 3 A, 1a					
output	SSR	12 VDC=±2 V, ≤ 20 mA					
Alarm o	utput	250 VAC∼1 A 1a					
Display	type	7 Segment (red, green), LED type					
Control type	Heating, Cooling	ON/OFF, P, PI, PD, PID Control					
Hysteres	sis	1 to 100 (0.1 to 50.0) °C/°F					
Proporti (P)	onal band	0.1 to 999.9 °C/°F					
Integral	time (I)	0 to 9,999 sec					
Derivati	ve time (D)	0 to 9,999 sec					
Control	cycle (T)	0.5 to 120.0 sec					
Manual	reset	0.0 to 100.0%					
Relay	Mechanical	≥ 5,000,000 operations					
life cycle	Electrical	OUT1/2: \geq 200,000 operations (load resistance: 250 VAC \sim 3 A) AL1/2: \geq 300,000 operations (load resistance: 250 VAC \sim 1 A)					
Dielectri	c strength	Between the charging part and the case: 1,000 VAC \sim 50/60 Hz for 1 min	Between the charging part and the case: 2,000 VAC \sim 50/60 Hz for 1 min				
Vibratio	n	$0.75\mathrm{mm}$ amplitude at frequency of 5 to 55 Hz in each X, Y, Z direction for 2 hours					
Insulation resistant		≥ 100 MΩ (500 VDC== megger)					
Noise im	ımunity	±2 kV square shaped noise (pulse width: 1 µs) by noise simulator R-phase, S-phase					
Memory	retention	pprox 10 years (non-volatile semiconductor memory type)					
Ambient temperature		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)					
Ambient humidity		35 to 85%RH, storage: 35 to 85%RF	H (no freezing or condensation)				
Insulation type		Mark: □, double or reinforced insulation (dielectric strength between the measuring input part and the power part: 1 kV)	Mark: , double or reinforced insulation (dielectric strength between the measuring input part and the power part: 2 kV)				
Certifica	tion	C E EK : SN us ENE ©					
Unit wei		• TCN4S: ≈ 100 g (≈ 147 g)	• TCN4M: ≈ 133 g (≈ 203 g)				
, r		• TCN4H: ≈ 124 g (≈ 194 g)	• TCN4L: ≈ 179 g (≈ 275 g)				

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type		Decimal point	Display	Using range (°C)	Using range (°F)
	K (CA)	1	F.C. A.H	-50 to 1,200	-58 to 2,192
	I (CA)	0.1	L C U'T	-50.0 to 999.9	-58.0 to 999.9
	J (IC)	1	JI C.H	-30 to 800	-22 to 1,472
	J (IC)	0.1	JI C.L	-30.0 to 800.0	-22.0 to 999.9
Thermo	L (IC)	1	LI C.H	-40 to 800	-40 to 1,472
-couple		0.1	LI C.L	-40.0 to 800.0	-40.0 to 999.9
	T (CC)	1	E C C.H	-50 to 400	-58 to 752
		0.1	E C C.L	-50.0 to 400.0	-58.0 to 752.0
	R (PR)	1	r P r	0 to 1,700	32 to 3,092
	S (PR)	1	5Pr	0 to 1,700	32 to 3,092
	CUEDO	1	C U 5.H	-50 to 200	-58 to 392
DTD	Cu50 Ω	0.1	C U 5.L	-50.0 to 200.0	-58.0 to 392.0
RTD	DPt100 Ω	1	dPt.H	-100 to 400	-148 to 752
	DE(100 ()	0.1	dPE.L	-100.0 to 400.0	-148.0 to 752.0

■ Display accuracy

Display accuracy					
Input type	Using temperature	Display accuracy			
Thermocouple	At room temperature (23°C ±5°C)	$ \begin{array}{l} (\text{PV}\pm0.5\%\text{or}\pm1^{\circ}\text{C}\text{higherone})\pm1\text{-digit} \\ \bullet\text{Thermocouple}\text{R,S}\text{below}200^{\circ}\text{C:} \\ (\text{PV}\pm0.5\%\text{or}\pm3^{\circ}\text{C}\text{higherone})\pm1\text{-digit} \\ \text{Over}200^{\circ}\text{C:} \\ (\text{PV}\pm0.5\%\text{or}\pm2^{\circ}\text{C}\text{higherone})\pm1\text{digit} \\ \bullet\text{Thermocouple}\text{L,RTD}\text{Cu}50\Omega: \\ (\text{PV}\pm0.5\%\text{or}\pm2^{\circ}\text{C}\text{higherone})\pm1\text{-digit} \end{array} $			
RTD	Out of room temperature range	$ (PV\pm0.5\% \text{ or } \pm2^{\circ}\text{C higher one}) \pm1\text{-digit} \\ \bullet \text{Thermocouple R, S below } 200^{\circ}\text{C:} \\ (PV\pm1.0\% \text{ or } \pm6^{\circ}\text{C higher one}) \pm1\text{digit} \\ \text{Over } 200^{\circ}\text{C:} \\ (PV\pm0.5\% \text{ or } \pm5^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{Thermocouple I, RTD } \text{Cu}50\Omega\text{:} \\ (PV\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{Thermocouple II}, \text{ RTD } \text{Cu}50\Omega\text{:} \\ \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{Thermocouple II}, \text{ RTD } \text{Cu}50\Omega\text{:} \\ \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{Thermocouple II}, \text{ RTD } \text{Cu}50\Omega\text{:} \\ \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{Thermocouple II}, \text{ RTD } \text{Cu}50\Omega\text{:} \\ \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\ \bullet \text{(PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm1\text{digit} \\$			

- For TCN4S- \Box -P, add $\pm 1^{\circ}$ C by accuracy standard. If the input specification is set to 'decimal point 0.1' display, add $\pm 1^{\circ}$ C by accuracy standard.

Unit Descriptions



1. PV Display part (red)

- RUN mode: Displays PV (Present value)
- Setting mode: Displays parameter name

2. SV Display part (green)

- RUN mode: Displays SV (Setting value)
- $\bullet \, \mathsf{Setting} \, \mathsf{mode:} \, \mathsf{Displays} \, \mathsf{parameter} \, \mathsf{setting} \, \mathsf{value} \,$

3. Indicator

Display	Name	Description
AL1/2	Alarm output	Turns ON when the alarm output is ON.
OUT	Control output	Turns ON when control output is ON • CYCLE/PHASE control of SSR drive output: Turns ON when MV is over 3.0% [AC power model]
AT	Auto tuning	Flashes during auto tuning every 1 sec
°C, °F	Unit	Displays selected unit (parameter).

4. Input key

Display	Name
[MODE]	Mode key
$[\blacktriangleleft], [\blacktriangledown], [\blacktriangle]$	Setting value control key

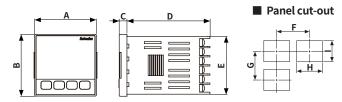
Errors

Display	Description	Troubleshooting
oPEn	Flashes when input sensor is disconnected or sensor is not connected.	Check input sensor status.
нннн	Flashes when PV is higher than input range. (11)	When input is within the rated input
LLLL	Flashes when PV is lower than input range. 01)	range, this display disappears.

01) Be careful that when HHHH / LLLL error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type.

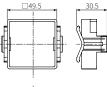
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TCN4S Series .



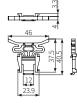
	Body			Panel cut-out					
	Α	В	С	D	E	F	G	Н	I
TCN4S	48	48	6	64.5	44.8	≥ 65	≥ 65	45 ^{+0.6}	45 ^{+0.6}
TCN4S-□-P	48	48	7.7	65.8	44.8	≥ 65	≥ 65	45 ^{+0.6}	45 ^{+0.6}
TCN4M	72	72	6	64.5	67.5	≥ 90	≥ 90	68 ^{+0.7}	68 ^{+0.7}
TCN4H	48	96	6	64.5	91.5	≥ 65	≥ 115	45 ^{+0.6}	92 0 0
TCN4L	96	96	6	64.5	91.5	≥ 115	≥ 115	92+0.8	92 0

■ Bracket TCN4S









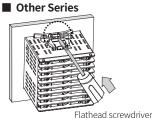
Other Series

Installation Method

■ TCN4S







Insert the unit into a panel, fasten the bracket by pushing with a flathead screwdriver.

Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape.







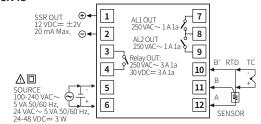
Wire ferrule

Terminal number 1 to 8 ≤ 3.7 9 to 11 ≤ 4.2 12 to 14 6 to 8

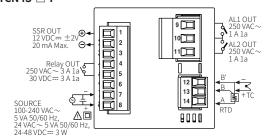
Fork crimp terminal Round crimp terminal

Connections

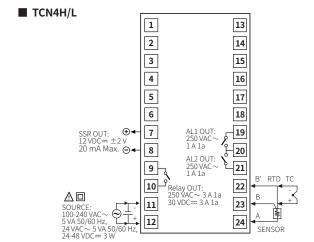
■ TCN4S



■ TCN4S-□-P

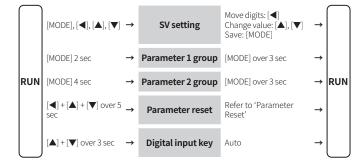


■ TCN4M 1 10 2 11 3 12 AL1 OUT: 250 VAC ~ 1 A 1a SSR OUT: 6 12 VDC= ±2V 20 mA Max. 4 (+) 13 5 **14** (-) **-**AL2 OUT: 250 VAC ~ 15 Relay OUT: 250 VAC ~ 3 A 1a 30 VDC == 3 A 1a 1 A 1a B' RTD TC 16 $\Delta \Box$ 17 8 SOURCE: 100-240 VAC~ 5 VA 50/60 Hz, 24 VAC~ 5 VA 50/60 Hz, 24-48 VDC== 3 W



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Mode Setting



Parameter Reset

- 01. Press the [◀] + [▲] + [▼] keys for over 5 sec. in run mode, INIT turns ON.
- 02. Change the setting value as YES by pressing the [▲], [▼] keys.
- 03. Press the [MODE] key to reset all parameter values as default and to return

Parameter Setting

- Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the description of each item.
- \bullet The setting range in parentheses is for using the decimal point display in the input specification.
- If there is no key input for more than 30 seconds in each parameter, it returns to RUN
- When pressing the [MODE] key within 1 second after returning to the operation mode from the parameter group, it will enter the parameter group before returning.
- [MODE] key: Saves the current parameter setting value and moves to the next parameter.
- $[\blacktriangleleft]$ key: Checks the fixed item / Moves the row when changing the set value
- [lacktriangle], [lacktriangle] keys: Selects the parameter / Changes the set value
- Recommended parameter setting sequence: Parameter 2 group \rightarrow Parameter 1 group → SV setting mode

■ Parameter 1 group

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SENSOR

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Par	Parameter Displa		Default	Setting range	Condition
1-1	AL1 alarm temperature	ALI	1250	Deviation alarm: -F.S. to F.S. °C/°F	2-12/14 alarm
1-2	AL2 alarm temperature	AL2	1250	Absolute value alarm: Within input range	operation: AM1 to AM6
1-3	Auto tuning	ЯĿ	oFF	OFF: Stop, ON: Execution	
1-4	Proportional band	ρ	0 10.0	0.1 to 999.9 °C/°F	2-8 Control
1-5	Integral time	1	0000	0 (OFF) to 9999 sec	type: PID
1-6	Derivative time	Ь	0000	0 (OFF) to 9999 sec	
1-7	Manual reset	r E S E	050.0	0.0 to 100.0%	2-8 Control type: PID & 1-5 Integral time: 0
1-8	Hysteresis	Н У 5	002	1 to 100 (0.1 to 50.0) °C/°F	2-8 Control type: ONOF

■ Parameter 2 group

	Parameter	2 grou	р		
Para	meter	Display	Default	Setting range	Condition
2-1	Input specification 01)	In-E	F.C. U.H	Refer to 'Input Type and Using Range'.	-
2-2	Temperature unit ⁰¹⁾	Unle	٥٥	°C, °F	-
2-3	Input correction	In-b	0000	-999 to 999 (-199.9 to 999.9) °C/°F	-
2-4	Input digital filter	ñ R u.F	000.1	0.1 to 120.0 sec	-
2-5	SV low limit ⁰²⁾	L-5u	- 50	Within 2-1 Input specification Input	-
2-6	SV high limit ⁰²⁾	H-5u	1200	range, L-SV ≤ H-SV - 1-digit °C/°F H-SV ≥ L-SV + 1-digit °C/°F	-
2-7	Control output mode ⁰³⁾	o-Ft	неяь	HEAT: Heating, COOL: Cooling	-
2-8	Control type 04)	[-ñd	PId	PID, ONOF: ON/OFF	-
2-9	Control output	oUt	rly	RLY: relay, SSR	-
2-10	SSR drive output type	55r.ñ	5tnd	[AC model] STND: standard, CYCL: cycle, PHAS: phase	2-9 Control output: SSR
2-11	Control cycle	Ł	2 0.0	0.5 to 120.0 sec	2-9 Control output: RLY 2-10 SSR drive output type: STND
	- common cycle		2.0	0.5 to 120.0 5.00	2-9 Control output: SSR 2-10 SSR drive output type: STND
2-12	AL1 alarm operation	AL-1	Aā!A MOD■	AM0: Off AM1: Deviation high limit alarm AM2: Deviation low limit alarm AM3: Deviation low limit alarm AM3: Deviation high, low limit alarm AM4: Deviation high, low reverse alarm AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm SBA: Sensor break alarm LBA: Loop break alarm (LBA)	-
2-13	AL1 alarm option			A: Standard alarm C: Standby sequence 1 E: Standby sequence 1 F: Alarm latch and standby sequence 1 F: Alarm latch and standby sequence 2 • Enter to option setting: Press [◀] key	-
				in 2-12 AL-1 alarm operation.	
2-14	AL2 alarm operation	0, 7	0-70	Same as 2-12/13 AL1 alarm operation/	
2-15	AL2 alarm option	AL-2	H n Z.H	option	=
2-16	Alarm output hysteresis	янч5	001	1 to 100 (0.1 to 50.0) °C/°F	2-12/14 AL1/2 alarm operation: AM1 to 6
2-17	LBA time	L b A.E	0000	0 (OFF) to 9999 sec or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA
2-18	LBA band	L b A.b	0002	0 (OFF) to 999 (0.0 to 999.9) °C/°F or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA & 2-18 LBA time: > 0
2-19	Digital input key	91 - F	StoP	STOP: Stop control output, AL.RE: Alarm reset, AT*: Auto tuning execution, OFF	*2-8 Control type: PID
2.20	Sensor error	Er.ñu	0 0 0.0	0.0: OFF, 100.0: ON	2-8 Control type: ONOF
2-20	MV	E F.NU	U U U.U	0.0 to 100.0%	2-8 Control type: PID
2-21	Lock	LoC	oFF	OFF LOC1: Parameter 2 group lock LOC2: Parameter 1/2 group lock LOC3: Parameter 1/2 group, SV setting lock	-

Function: Alarm

888.8 Alarm Alarm operation option Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

Operation

• **H**: Alarm output hysteresis

Mode	Name	Alarm operation		Description		
AVO	-	-		No alarm output		
Añ I	Deviation high limit	OFF H ON SV PV 100°C 110°C High deviation: Set as 10°C	OFF H ON PV SV 90°C 100°C High deviation: Set as -10°C	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.		
A y S	Deviation low limit	ON THU OFF PV SV 90°C 100°C Low deviation: Set as 10°C	ON THE OFF SV PV 100°C 110°C Low deviation: Set as -10°C	If deviation between PV and SV as low limit is higher than set value of deviation temperature, the alarm output will be ON.		
A i 3	Deviation high, low limit	ON H ON		If deviation between PV and SV as high/low- limit is higher than set value of deviation temperature, the alarm output will be ON.		
ЯñЧ	Deviation high, low limit reverse	PV S 90°C 100	OFF H ON TH OFF			
A n S	Absolute value high limit	OFF H ON A PV 90°C 100°C Absolute value: Set as 90°C	OFF H ON SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is higher than the absolute value, the output will be ON.		
A n E	Absolute value low limit	ON H OFF PV SV 90°C 100°C Absolute value: Set as 90°C	ON TH OFF SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is lower than the absolute value, the output will be ON.		
56R	Sensor break	-		It will be ON when it detects sensor disconnection.		
LBA	Loop break	-		It will be ON when it detects loop disconnection.		

■ Option

	F							
Mode	Name	Description	Condition of reapply					
Я	Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-					
Ь	Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	=					
С	Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Power ON					
а	Alarm atch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second lalarm condition, alarm latch operates.	Power ON					
E	Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When reapplied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm					
F	Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	temperature / operation or change STOP to RUN mode					

Ol) Below parameters are initialized when the setting value is changed.

- Parameter 1 group: AL1/2 alarm temperature

- Parameter 2 group: Input correction, SV high/low limit, Alarm output hysteresis, LBA time, LBA band

- SV setting mode: SV

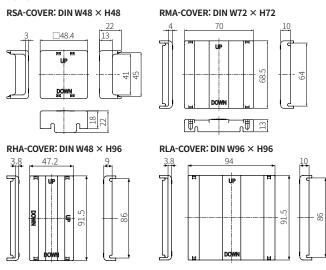
⁰²⁾ If SV is lower than low limit or higher than high limit when the value is changed, SV is changed to the low/high limit value.

If 2-1 Input specification is changed, the value is changed to Min./Max. value of Input specification.

⁰³⁾ When the setting value is changed, setting value of 2-20 Sensor error MV is initialized to 0.0 (OFF).
04) When changing the value from PID to ONOF, each value of following parameter is changed.
2-19 Digital input key: OFF, 2-20 Sensor error MV: 0.0 (when setting value is lower than 100.0)

Sold Separately: Terminal Protection Cover

• Unit: mm



Segment Table

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

√¶ ¤‡

7 segment				11 segment				12 segment				16 segment			
0	0	1	П	0	0	1	Ι	0	0	1	T	0	0	Ι	1
-1	1	J	J	-1	1	J	J	-1	1	J	J	-1	1	υŢ	J
2	2	F	K	2	2	К	K	2	2	К	K	2	2	K	K
3	3	L	L	3	3	L	L	3	3	L	L	3	3	L	L
4	4	ñ	М	4	4	М	М	4	4	М	М	4	4	М	М
5	5	n	N	5	5	N	N	5	5	N	N	5	5	И	N
5	6	0	0	Б	6	0	0	Б	6	0	0	Б	6	0	0
7	7	Ρ	Р	7	7	ρ	Р	7	7	Р	Р	7	7	ρ	Р
8	8	9	Q	8	8	0	Q	8	8	O	Q	8	8	Q	Q
9	9	٢	R	9	9	R	R	9	9	R	R	9	9	ĸ	R
R	Α	5	S	Я	Α	5	S	Я	Α	5	S	Я	Α	5	S
Ь	В	Ł	Т	Ь	В	Ł	Т	Ь	В	Ł	Т	3	В	T	Т
Ε	С	П	U	Ε	С	Ш	U	Ε	С	П	U	Е	С	Ш	U
Ь	D	נ	٧	Ь	D	V	٧	d	D	ľ	V	D	D	V	٧
Ε	Е	ñ	W	Ε	Е	И	W	Ε	Е	И	W	Ε	Е	И	W
F	F	4	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х
G	G	У	Υ	G	G	У	Υ	5	G	У	Υ	5	G	Y	Υ
Н	Н	Ξ	Z	Н	Н	Z	Z	Н	Н	Z	Ζ	Н	Н	2	Z